

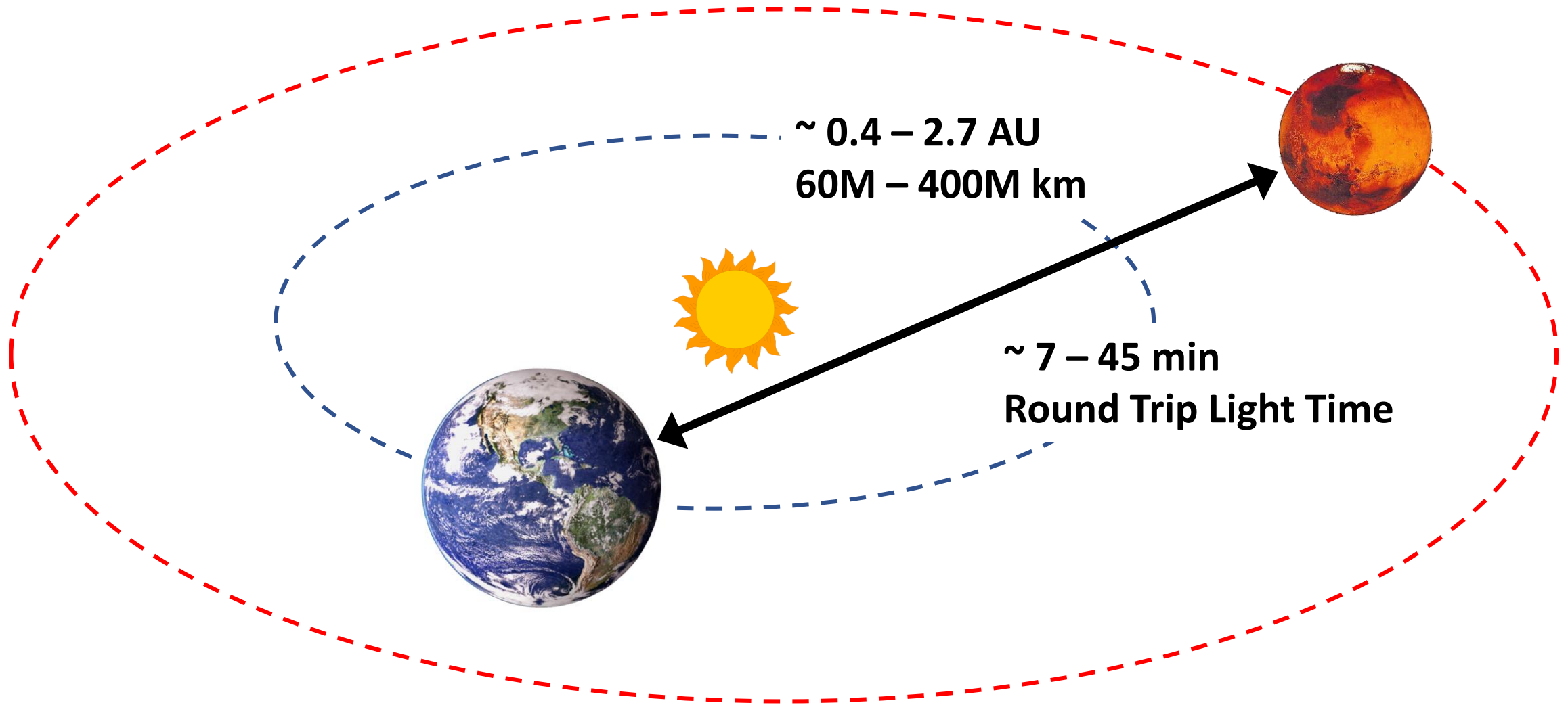
# Autonomous Vehicles for Mars Exploration

Chad Edwards  
Mars Exploration Program Formulation Office  
Aug 6, 2017



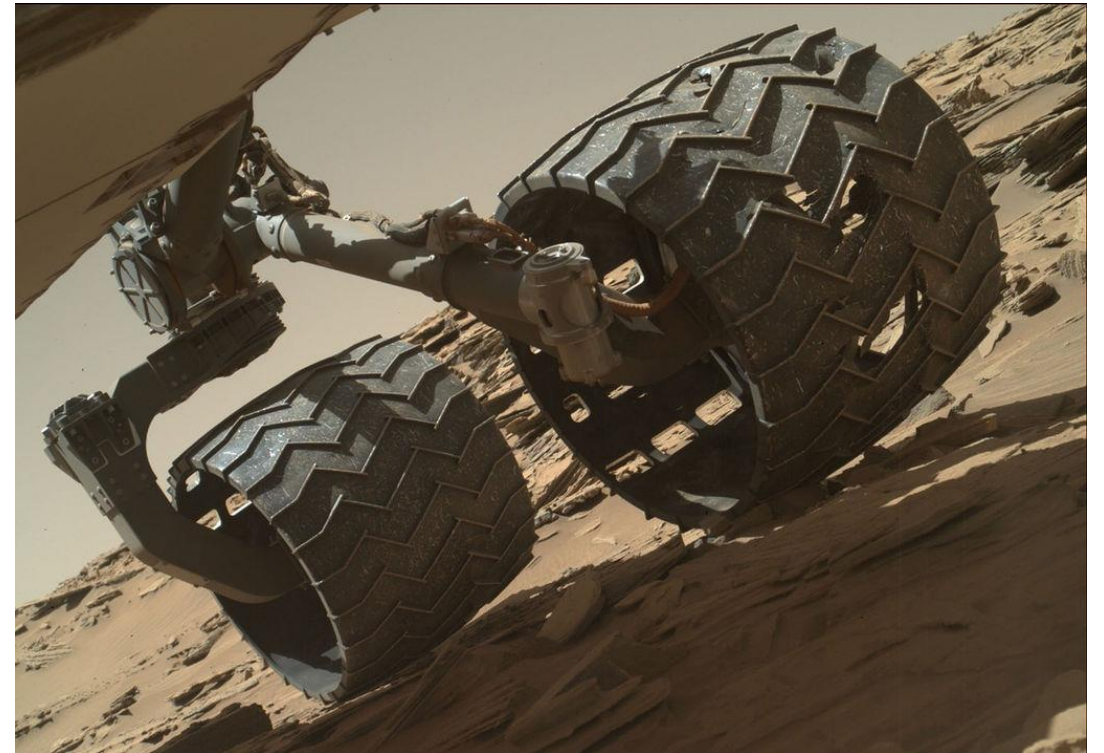
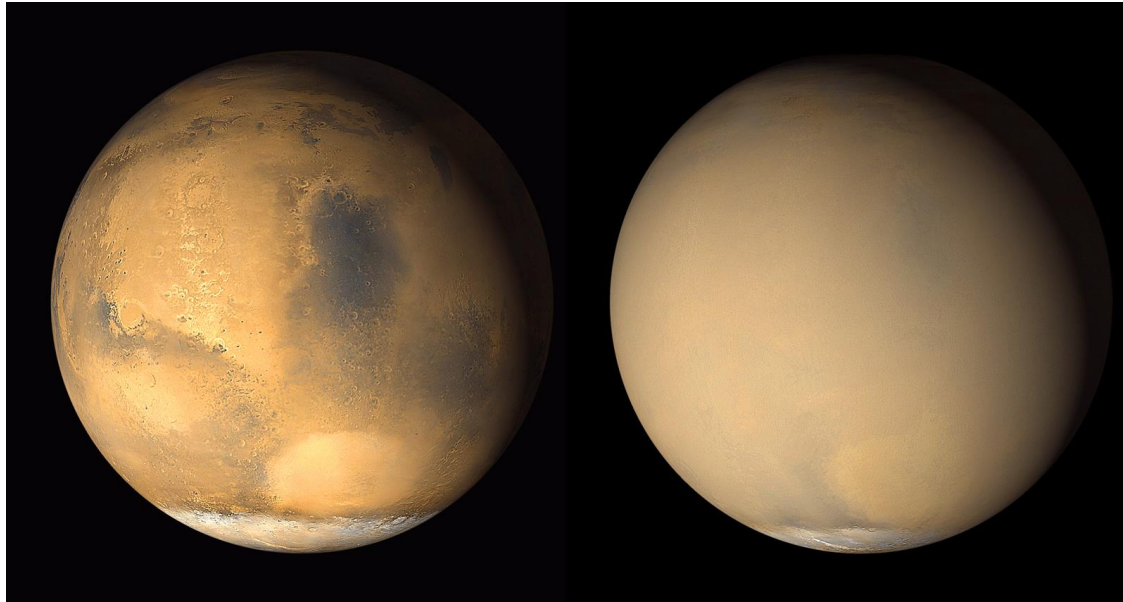
**Jet Propulsion Laboratory**  
California Institute of Technology

# Key drivers for autonomy: Long Round-Trip Light Time





# Key drivers for autonomy: Unpredictable Environments

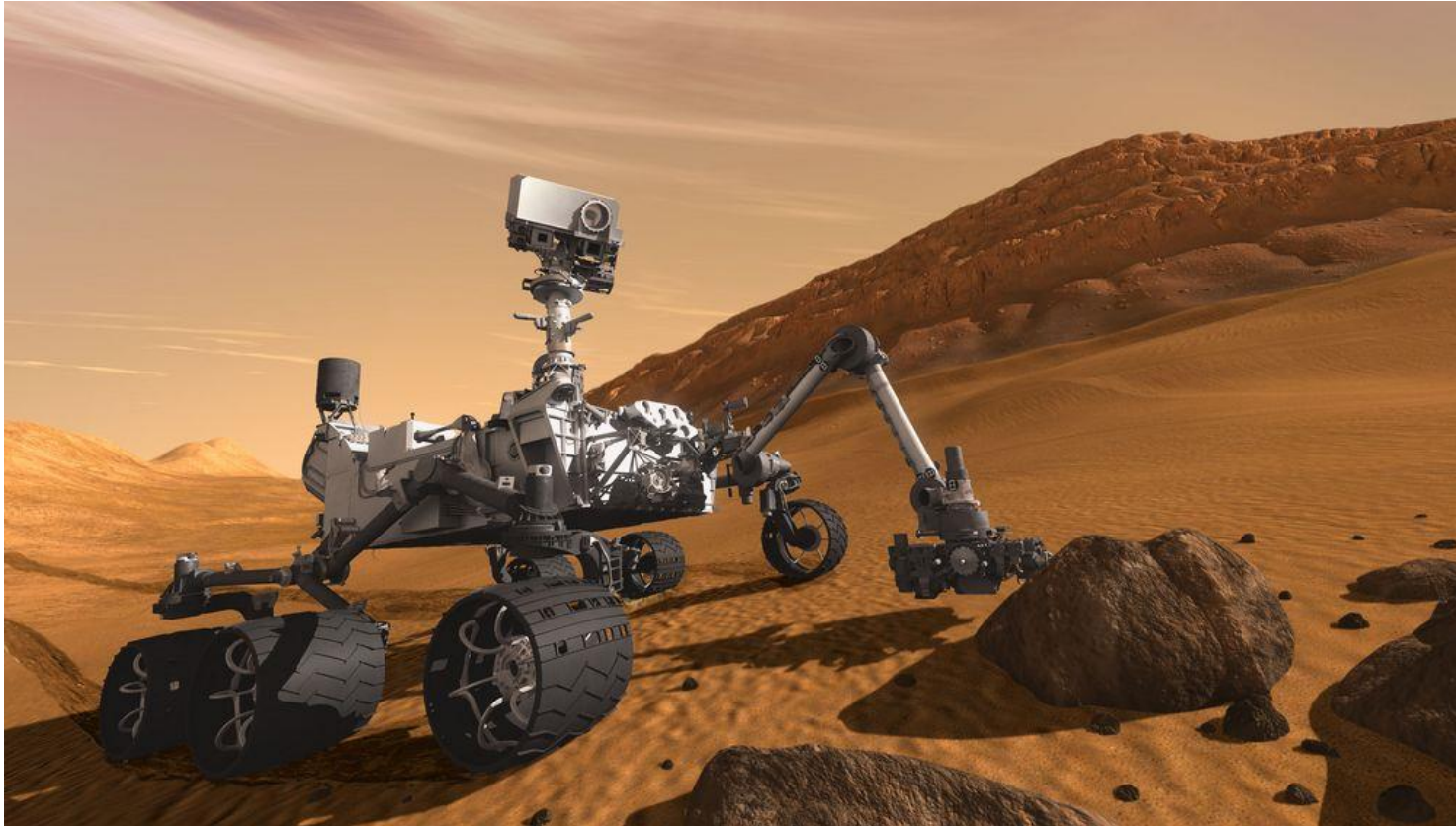


# Key drivers for autonomy: Contact Investigations



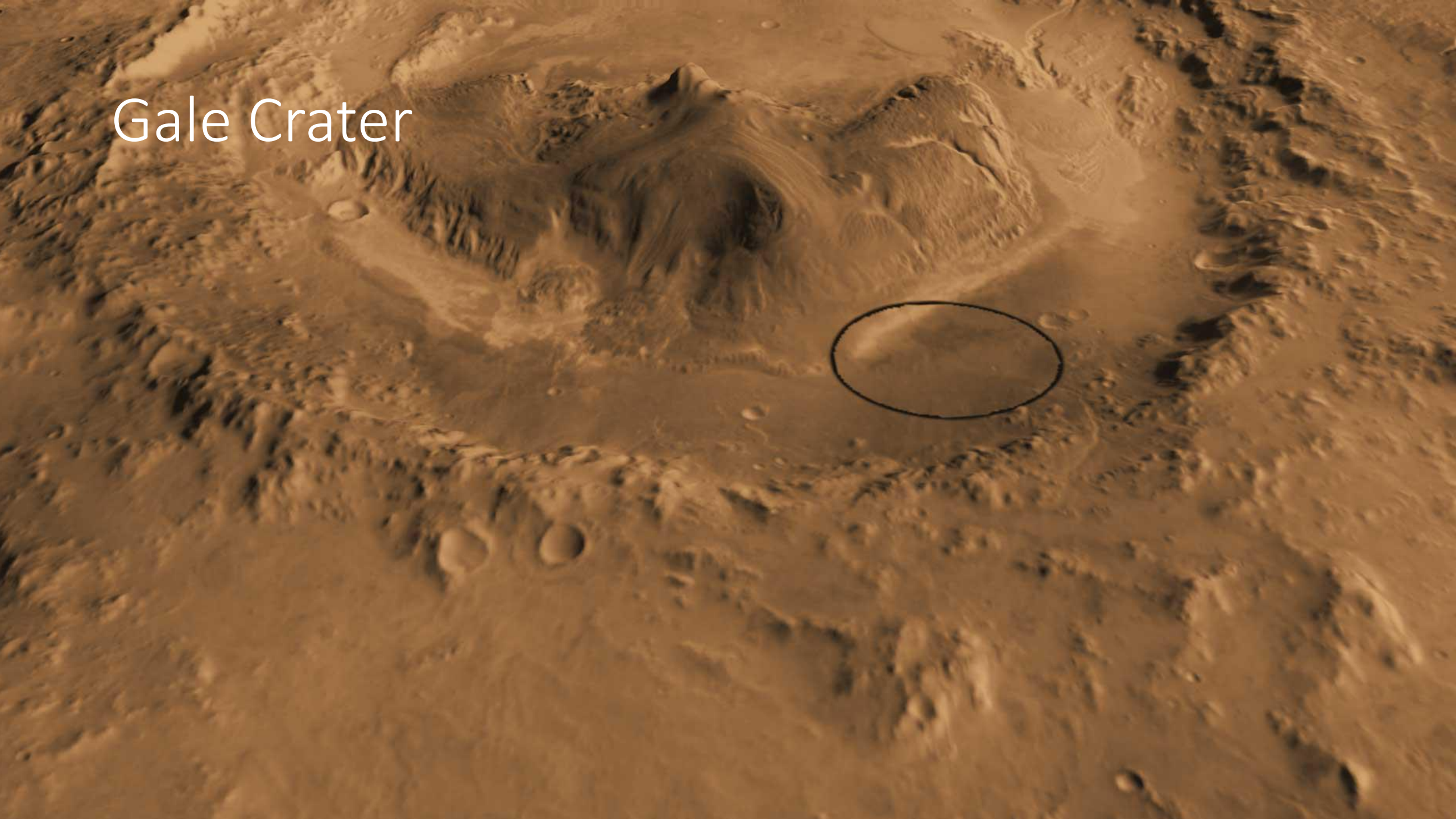


# Curiosity Rover



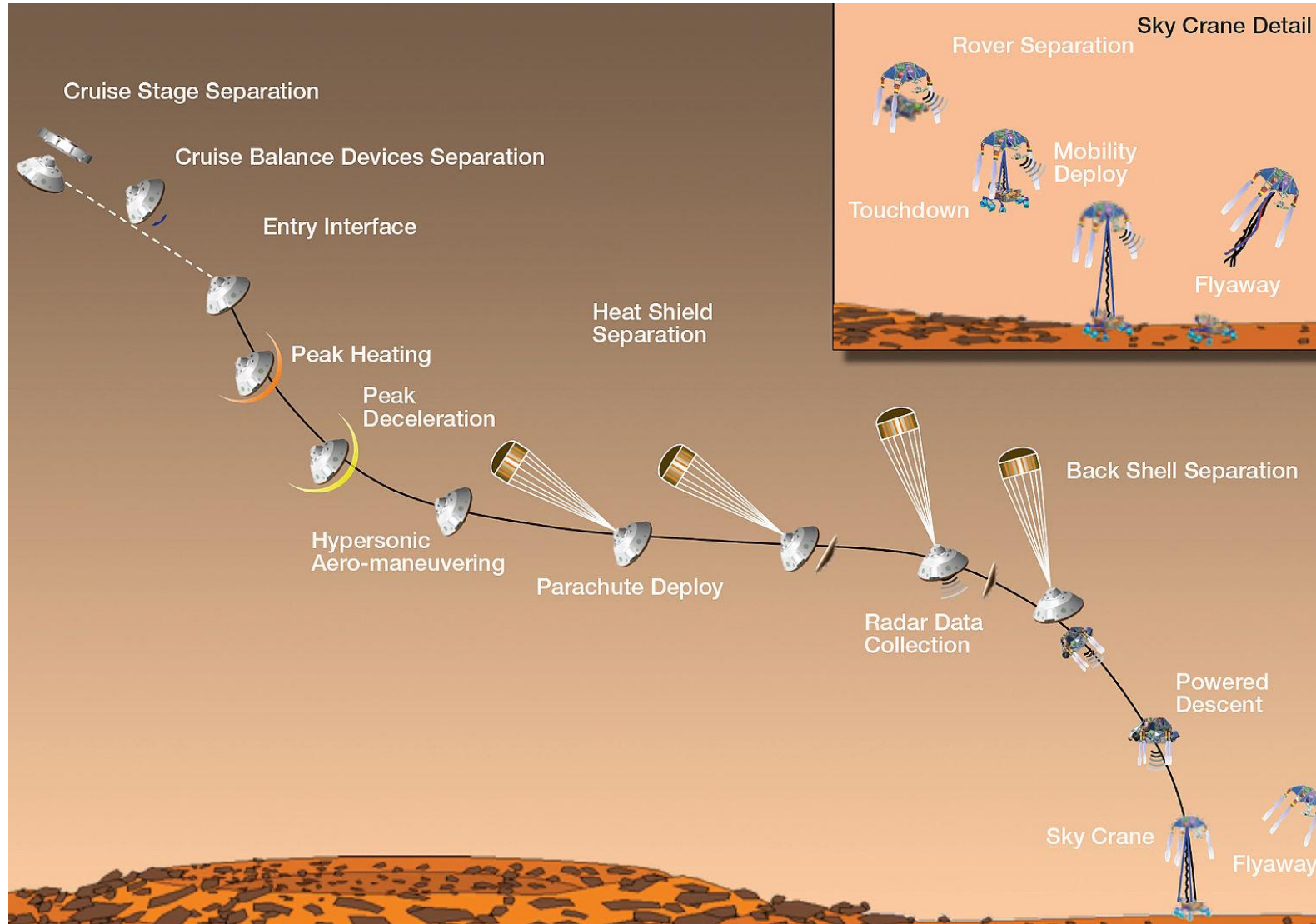
<b>Cameras</b>	<ul style="list-style-type: none"><li>• Mast Camera (Mastcam)</li><li>• Mars Hand Lens Imager (MAHLI)</li><li>• Mars Descent Imager (MARDI)</li></ul>
<b>Spectrometers</b>	<ul style="list-style-type: none"><li>• Alpha Particle X-Ray Spectrometer (APXS)</li><li>• Chemistry &amp; Camera (ChemCam)</li></ul>
<b>Analytical Instruments</b>	<ul style="list-style-type: none"><li>• Chemistry &amp; Mineralogy X-Ray Diffraction/X-Ray Fluorescence Instrument (CheMin)</li><li>• Sample Analysis at Mars (SAM) Instrument Suite</li></ul>
<b>Radiation Detectors</b>	<ul style="list-style-type: none"><li>• Radiation Assessment Detector (RAD)</li><li>• Dynamic Albedo of Neutrons (DAN)</li></ul>
<b>Environmental Sensors</b>	<ul style="list-style-type: none"><li>• Rover Environmental Monitoring Station (REMS)</li></ul>
<b>Atmospheric Sensors</b>	<ul style="list-style-type: none"><li>• Mars Science Laboratory Entry Descent and Landing Instrument (MEDLI)</li></ul>

# Gale Crater

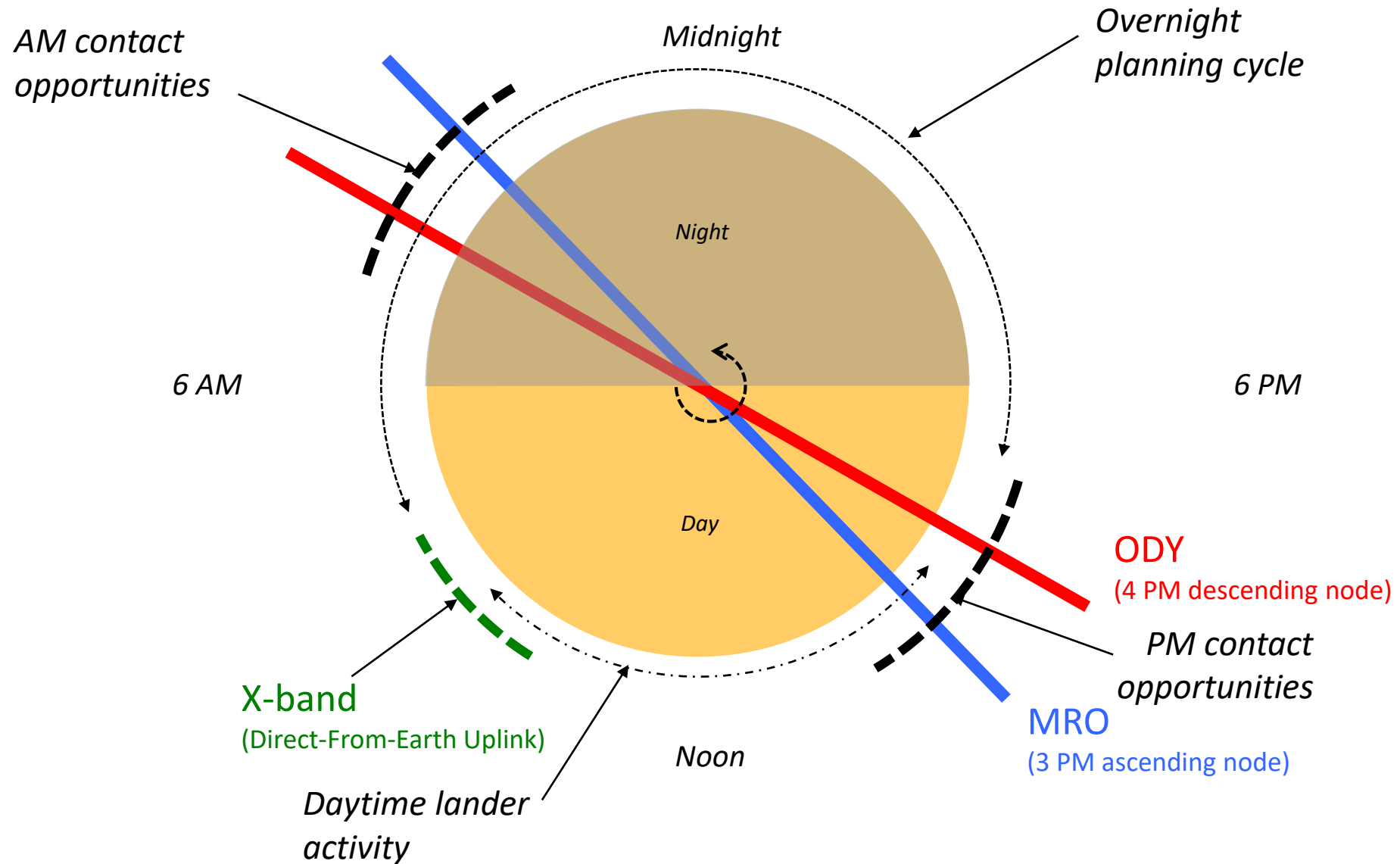




# Autonomy for Landing



# Rover Operations: Sol by Sol...



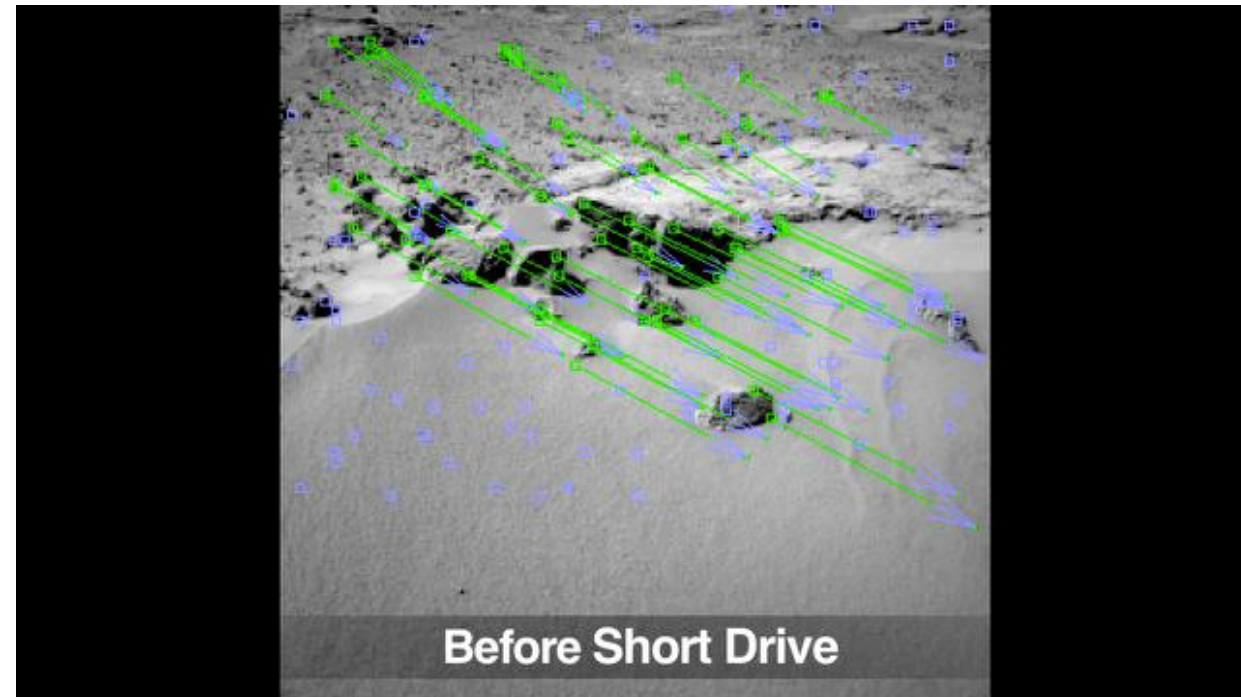


# Rover Navigation

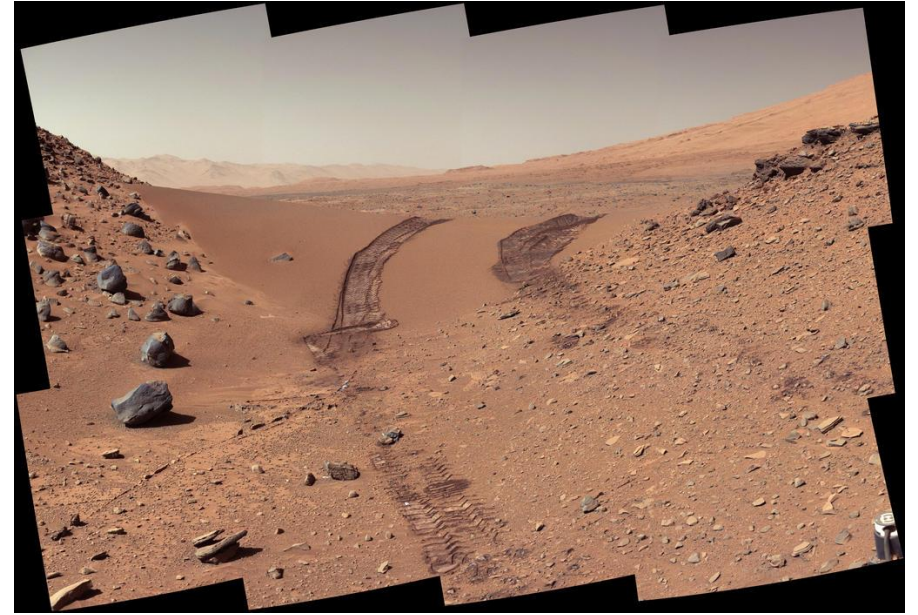


**AutoNav**

## Visual Odometry



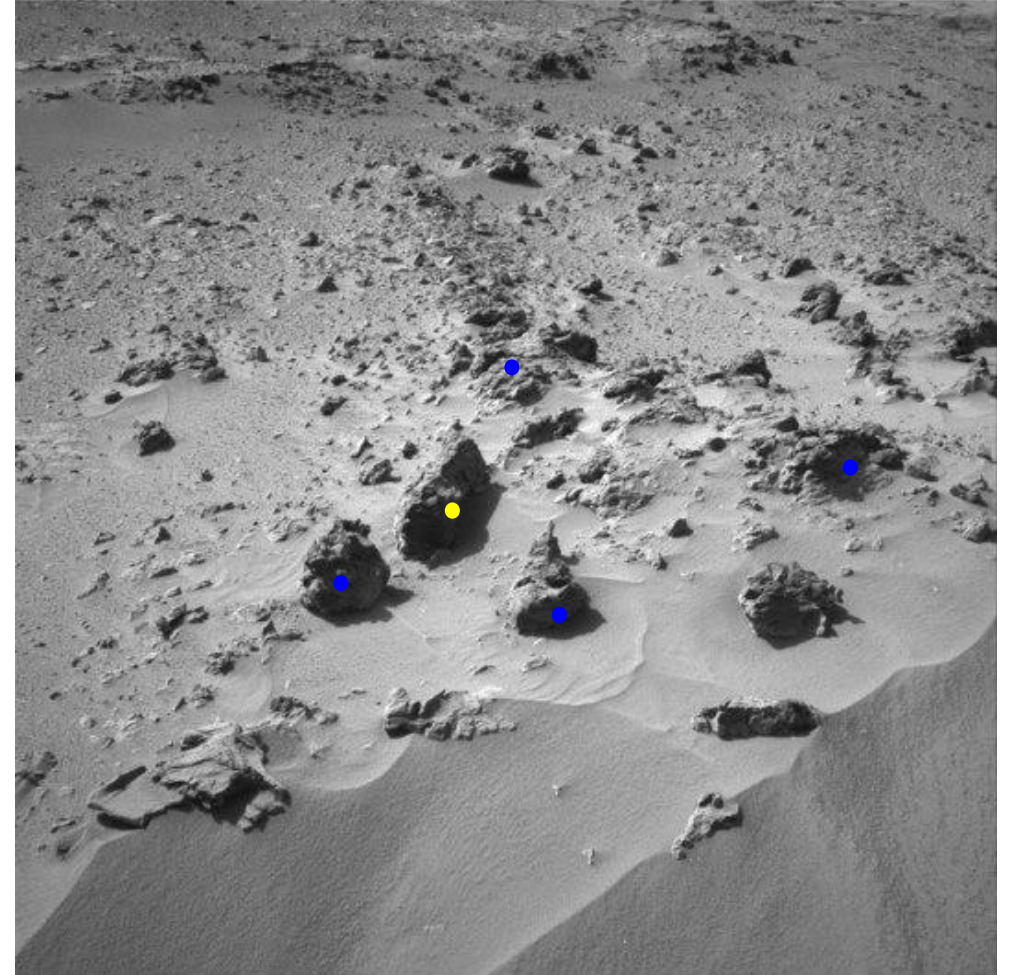
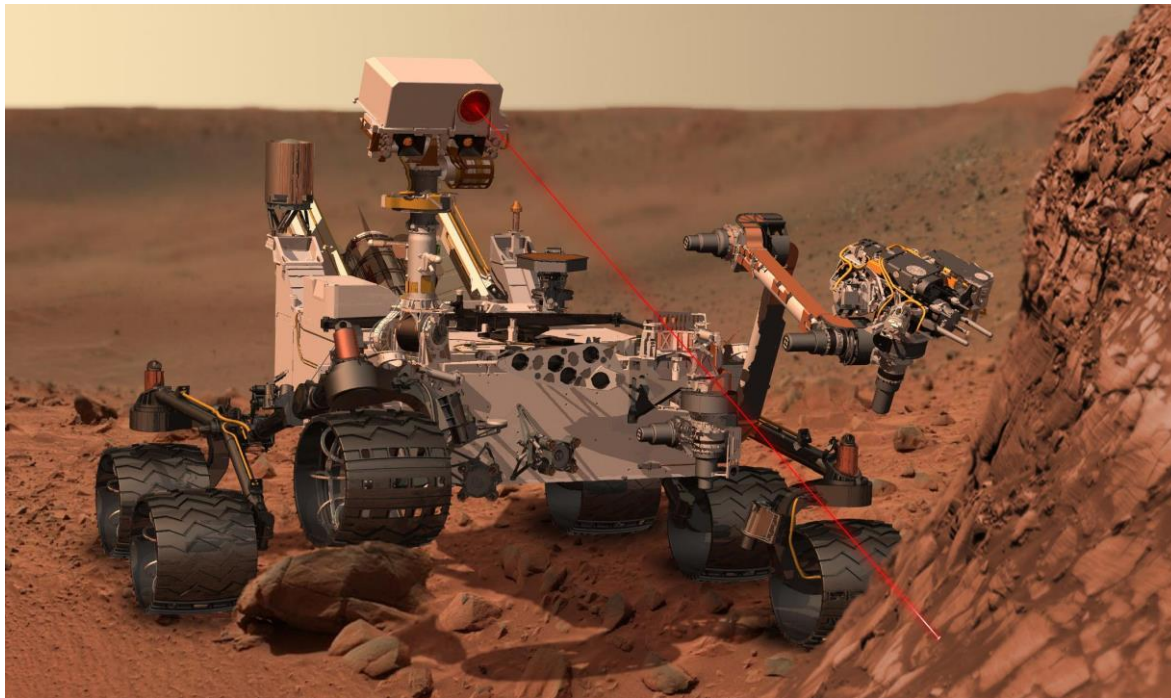
# Challenging Terrain...



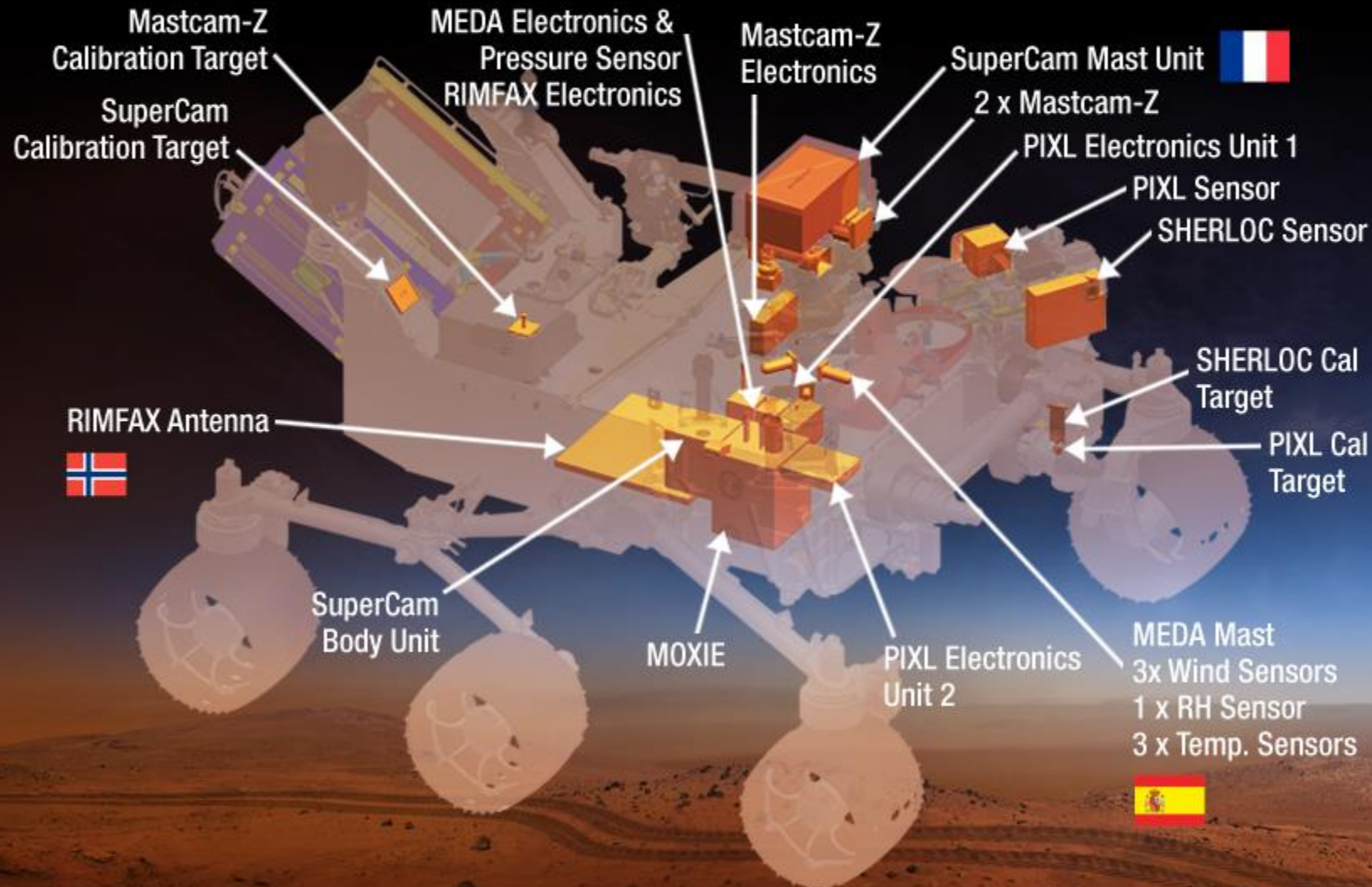


# Intelligent Science Acquisition

- AEGIS = “Autonomous Exploration for Gathering Increased Science”
  - Currently supporting autonomous targeting of Curiosity ChemCam instrument

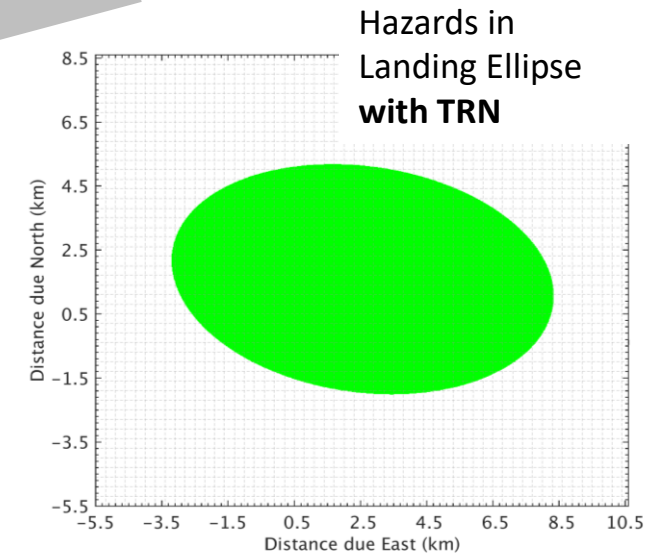
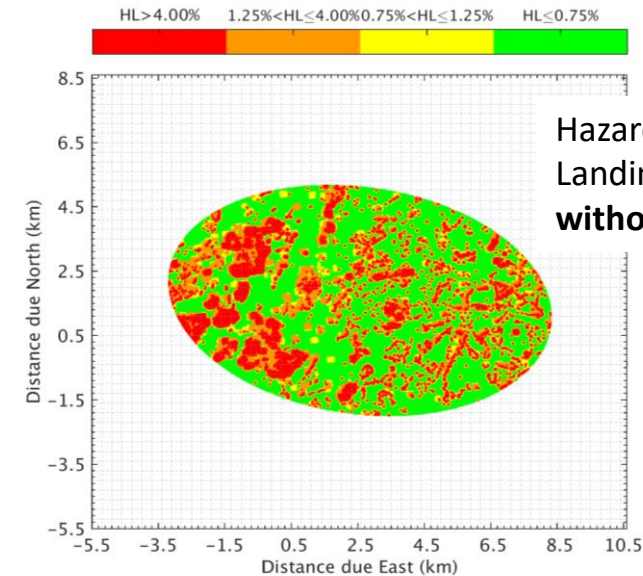
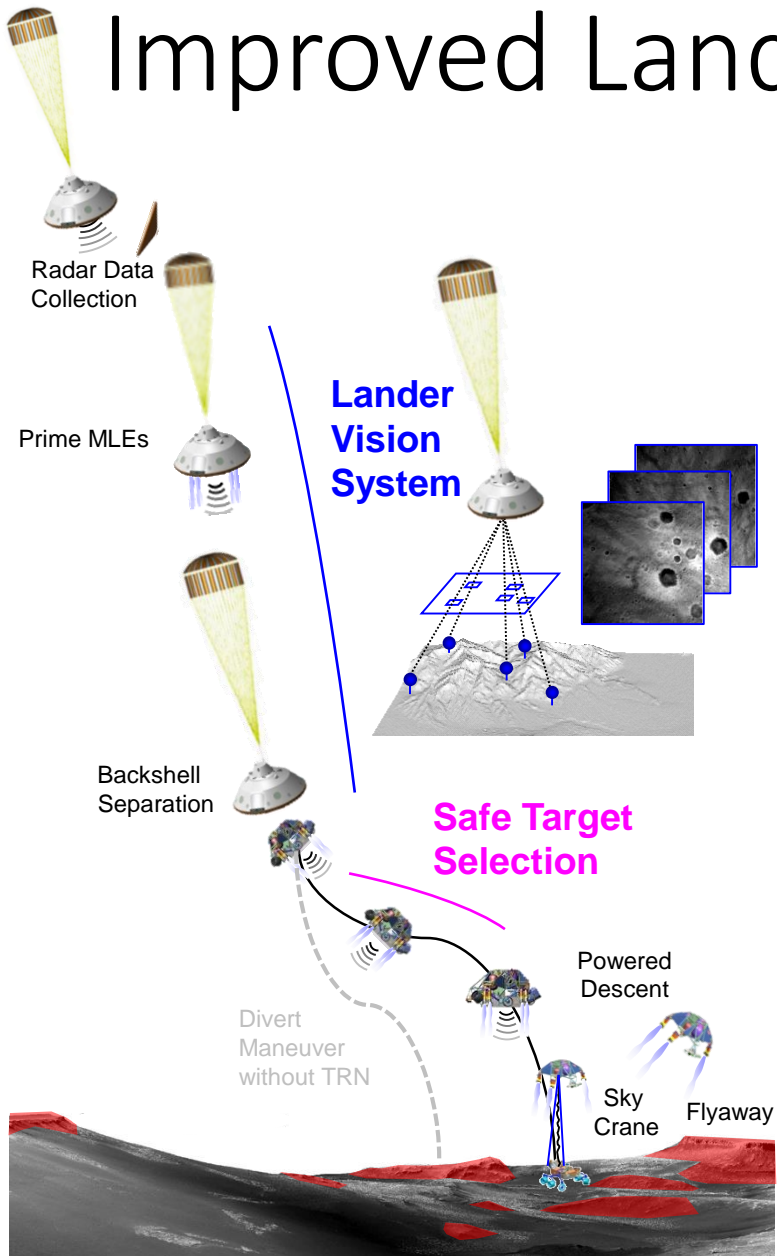


# Mars 2020 Rover





# Improved Landing: Terrain-Relative Navigation



# Mars Sample Return – Notional Architecture

## Mars 2020

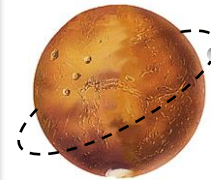
- Select & Acquire Samples
- Deposit samples for future retrieval



*Sample tube  
on Mars  
surface*

## MSR-Lander Concept

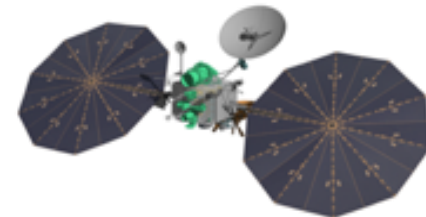
- Small Fetch Rover to Retrieve Samples
- Small MAV on Fixed Platform
- Launch Samples from Mars Surface to ~500km Orbit



*Orbiting  
Sample  
(OS)  
canister in  
Mars orbit*

## MSR-Orbiter Concept

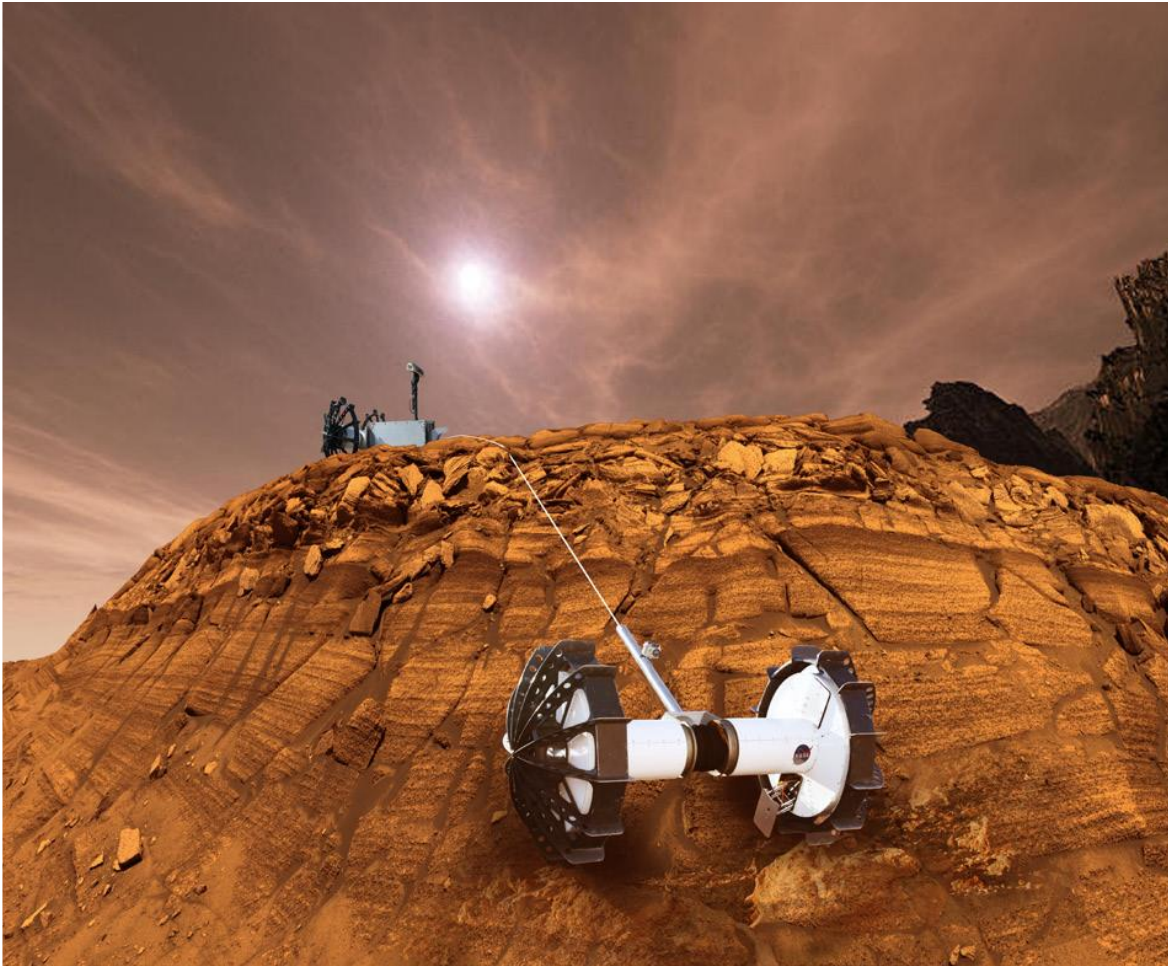
- Rendezvous & Sample Containment
- Return to Earth
- Earth Entry Vehicle



*Sample  
returned to  
earth*



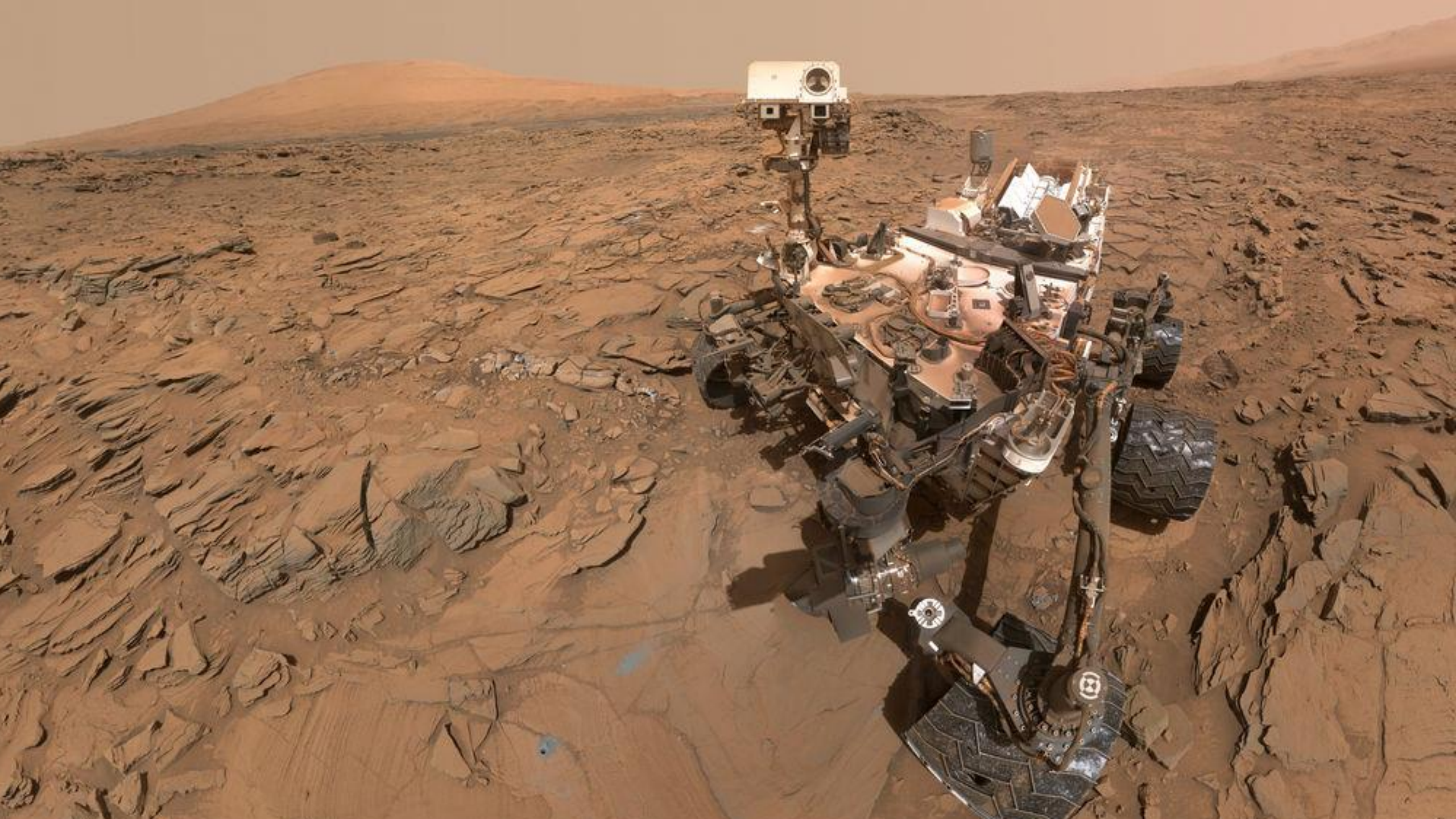
# Rapelling Rover Concepts for Extreme Terrain Access













**Jet Propulsion Laboratory**  
California Institute of Technology